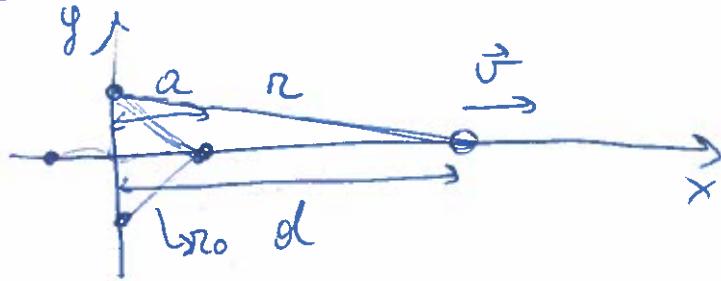


E.S.1/

4/2/2021

P.1



PER PARMETRIA LA

GRANDE SI

MUOVERE LUNGHEZZA

X POSITIVO

$$r = \sqrt{r^2 + d^2} \quad r_0 = \sqrt{q^2 + q^2} = q\sqrt{2}$$

$$T_f + U_f = T_i + U_i$$

$$\frac{1}{2} m v_f^2 + q V_f = \cancel{\frac{1}{2} m v_i^2 + q V_i}^{=0}$$

$$\frac{1}{2} m v_f^2 = -q (V_f - V_i) \rightarrow v_f = \sqrt{-\frac{2q}{m} (V_f - V_i)}$$

$$V_i = \frac{q}{4\pi\epsilon} \frac{1}{r_0} + \frac{q}{4\pi\epsilon} \frac{1}{r_0} + \frac{q}{4\pi\epsilon} \frac{1}{2a} = \frac{q}{4\pi\epsilon} \left( \frac{2}{r_0} + \frac{1}{2a} \right)$$

$$V_f = \frac{q}{4\pi\epsilon} \frac{1}{2} + \frac{q}{4\pi\epsilon} \frac{1}{2} + \frac{q}{4\pi\epsilon} \frac{1}{(a+d)} = \frac{q}{4\pi\epsilon} \left( \frac{2}{2} + \frac{1}{a+d} \right)$$

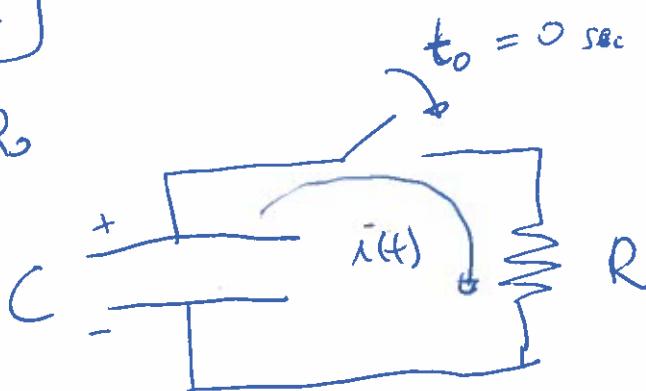
$$V_f - V_i = \frac{q}{4\pi\epsilon} \left( \frac{2}{2} + \frac{1}{a+d} - \frac{2}{r_0} - \frac{1}{2a} \right)$$

$$v_f = \sqrt{-\frac{2q^2}{4\pi\epsilon m} \left( \frac{2}{2} + \frac{1}{a+d} - \frac{2}{r_0} - \frac{1}{2a} \right)}$$

$$v_f = \sqrt{\frac{2q^2}{4\pi\epsilon m} \left( \frac{2}{a\sqrt{2}} + \frac{1}{2a} - \frac{2}{\sqrt{a^2+d^2}} - \frac{1}{d+a} \right)}$$

E.S. 2

$$Q_i = Q_0$$



P. 2

$$V_0 = \frac{Q_0}{C}$$

$$i(t) = \frac{V_0}{R} e^{-\frac{t}{\tau}} \quad \tau = RC$$

$$i(t) = \frac{Q_0}{RC} e^{-\frac{t}{RC}} \quad P(t) = i^2(t) R$$

$$U = V_{t_1 \rightarrow t_2} = \int_{t_1}^{t_2} i^2(t) R dt = \int_{t_1}^{t_2} \left( \frac{Q_0}{RC} \right)^2 R e^{-\frac{2t}{RC}} dt =$$

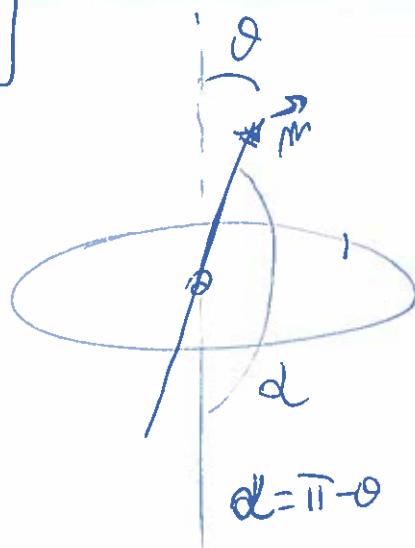
$$= \frac{Q_0^2}{RC^2} R \int_{t_1}^{t_2} e^{-\frac{2t}{RC}} dt = -\frac{Q_0^2}{RC^2} \frac{R}{2} \left( e^{-\frac{2t_2}{RC}} - e^{-\frac{2t_1}{RC}} \right) =$$

$$= \frac{Q_0^2}{2C} \left( e^{-\frac{2t_1}{RC}} - e^{-\frac{2t_2}{RC}} \right) = U$$

$$Q_0 = \sqrt{\frac{2UC}{\left( e^{-\frac{2t_1}{RC}} - e^{-\frac{2t_2}{RC}} \right)}}$$

ES.3

P.3



$$L_{\text{est}} > 0$$

per cui

$$L_{\text{est}} = -L_{\text{del campo } B} = -L_B$$

$$L_B = -\Delta U_m \rightarrow L_{\text{est}} = \Delta U_m$$

all'equilibrio  $\vec{m} \parallel \vec{B}$

$$(U_{m_{\text{min}}} = -\vec{m} \cdot \vec{B} = -mB)$$

$$L_{\text{est}} = U_{m_{\text{fin}}} - U_{m_{\text{ini}}} =$$

$$L_{\text{est}} \Rightarrow = \begin{cases} -mB \cos \theta + mB & \text{se } \vec{m} \text{ è ANTERIORE} \\ \text{oppure} \\ -mB \cos(\pi - \theta) + mB & \text{se } \vec{m} \text{ è DOPO} \end{cases}$$

$$= \begin{cases} -mB \cos(10^\circ) + mB = mB(1 - \cos(10^\circ)) > 0 \text{ è ANTER.} \\ -mB \cos(170^\circ) + mB = mB(1 - \cos(170^\circ)) > 0 \text{ è DOPO} \end{cases}$$

$\checkmark$  ANTER. BENE ENTROBI

$$\begin{aligned} B &= \frac{\mu_0 i_0}{2R} & \rightarrow B^+ &= \frac{\mu_0 i_0^+}{2R} \text{ (ANTER.)} \\ & & \rightarrow B^- &= \frac{\mu_0 i_0^-}{2R} \text{ (DOPO)} \end{aligned}$$

$$i_0^+ = \mu_0 \text{ ANTERIORE} : \quad L_{\text{est}} = m \frac{\mu_0 i_0^+}{2R} (1 - \cos \theta) \rightarrow$$

$$i_0^+ = \frac{2R L_{\text{est}}}{m \mu_0} \frac{1}{1 - \cos \theta}$$

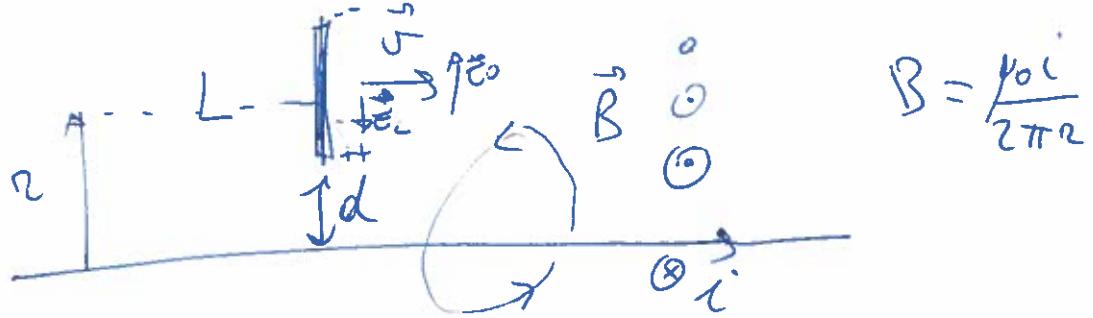
$$i_0^- = \mu_0 \text{ DOPO} : \quad L_{\text{est}} = m \frac{\mu_0 i_0^-}{2R} [1 - \cos(\pi - \theta)]$$

$$i_0^- = \frac{2R L_{\text{est}}}{m \mu_0} \frac{1}{1 - \cos(\pi - \theta)}$$

$$T^+ = 2\pi \sqrt{\frac{I}{m B^+}} \quad T^- = 2\pi \sqrt{\frac{I}{m B^-}}$$

ES. 4

P. 4



$$\vec{F}_{\text{Lorentz}} = q \vec{v} \times \vec{B} \quad \vec{E}_L = \frac{\vec{v}}{q} = \vec{v} \times \vec{B}$$

$$E_L(v) = -v \cdot \frac{\mu_0 i}{2\pi r} \quad E_L = -E_0 \quad \begin{aligned} & \left( \text{All'EQUILIBRIO} \right. \\ & \text{IL COMP. PUNTO} \\ & \text{A LORENZI} \text{ } \cancel{\text{SISTEMA}} \\ & \text{ALL'EQUILIBRIO} \\ & \text{DA QUESTO ESSERMO} \\ & \text{SI TUTTO} \end{aligned}$$

$$\Delta V = - \int_d^{d+L} \vec{E}_0 \cdot d\vec{l}$$

$$\Delta V = - \int_d^{d+L} -v \frac{\mu_0 i}{2\pi r} dr = -v \frac{\mu_0 i}{2\pi} \int_d^{d+L} \frac{dr}{r} =$$

$$V(d+L) - V(d) = - \frac{\mu_0 v i}{2\pi} \ln \left( \frac{d+L}{d} \right) = \frac{\mu_0 v i}{2\pi} \ln \left( \frac{d}{d+L} \right) < 0$$