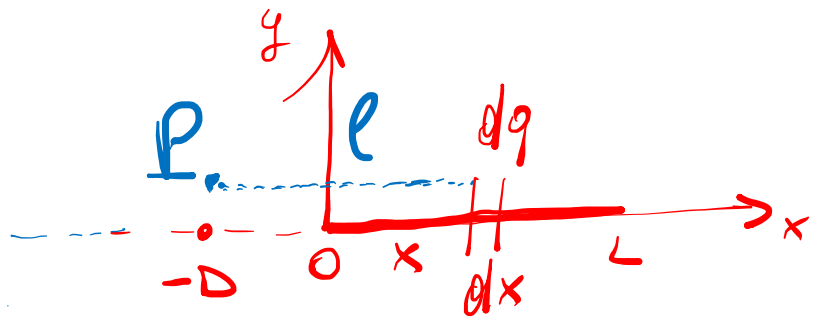


21-10-2021

P. 1

1)



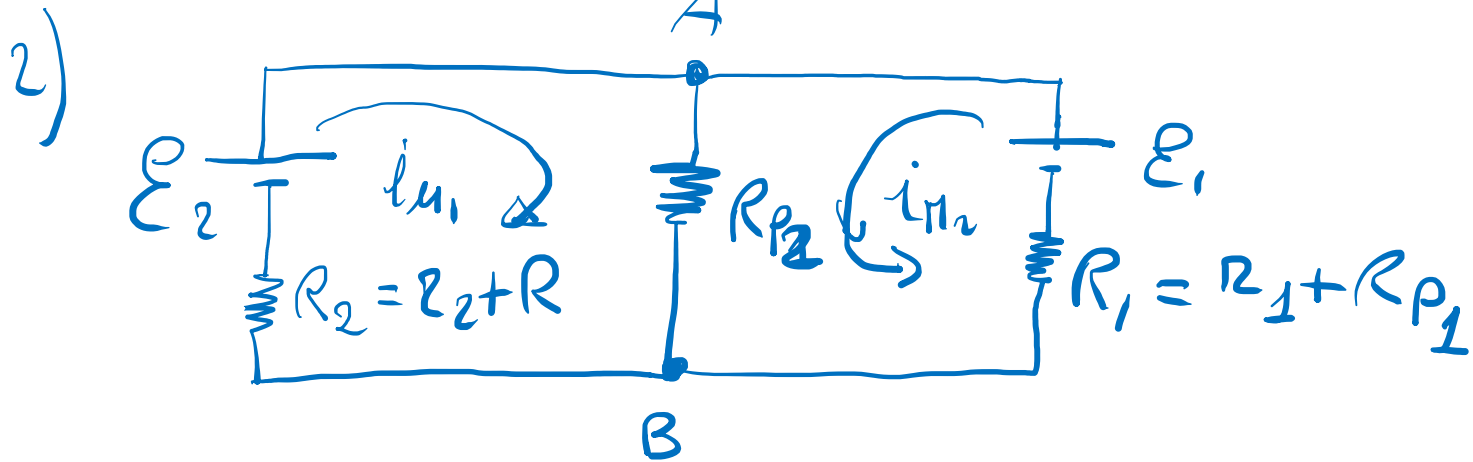
$$dq = \lambda(x) dx \quad \lambda = k(x+D)$$

$$dq = k(x+D) dx$$

$$k(x) = (x+D) \quad 0 \leq x \leq L$$

$$V(P) = \int_0^L \frac{dq(x)}{4\pi\epsilon_0 l} = \int_0^L \frac{k(x+D) dx}{4\pi\epsilon_0 (x+D)} = \frac{k}{4\pi\epsilon_0} \int_0^L dx = \frac{kL}{4\pi\epsilon_0}$$

$$\vec{E}(P) = -\hat{x} E(P) \quad E(P) = \int_0^L \frac{dq(x)}{4\pi\epsilon_0 e^2(x)} = \int_0^L \frac{k(x+D) dx}{4\pi\epsilon_0 (x+D)^2} = \frac{k}{4\pi\epsilon_0} \ln\left(\frac{l+D}{D}\right)$$



$$R_{P1} = \frac{1}{\frac{1}{R} + \frac{1}{2} + \frac{1}{2}} = \frac{R}{3} \quad \text{P.2}$$

$$R_{P2} = \frac{1}{\frac{1}{R} + \frac{1}{R}} = \frac{R}{2}$$

$$\begin{cases} \mathcal{E}_2 = R_{P2}(i_1 + i_2) + R_2 i_1 \\ \mathcal{E}_1 = R_{P2}(i_1 + i_2) + R_1 i_2 \end{cases} = \begin{cases} i_1(R_2 + R_{P2}) + i_2(R_{P2}) = \mathcal{E}_2 \\ i_1(R_{P2}) + i_2(R_1 + R_{P2}) = \mathcal{E}_1 \end{cases}$$

$$\Delta = (R_2 + R_{P2})(R_1 + R_{P2}) - (R_{P2})^2$$

$$\Delta_x = \mathcal{E}_2(R_1 + R_{P2}) - R_{P2}\mathcal{E}_1$$

$$\Delta_y = (R_2 + R_{P2})\mathcal{E}_1 - R_{P2}\mathcal{E}_2$$

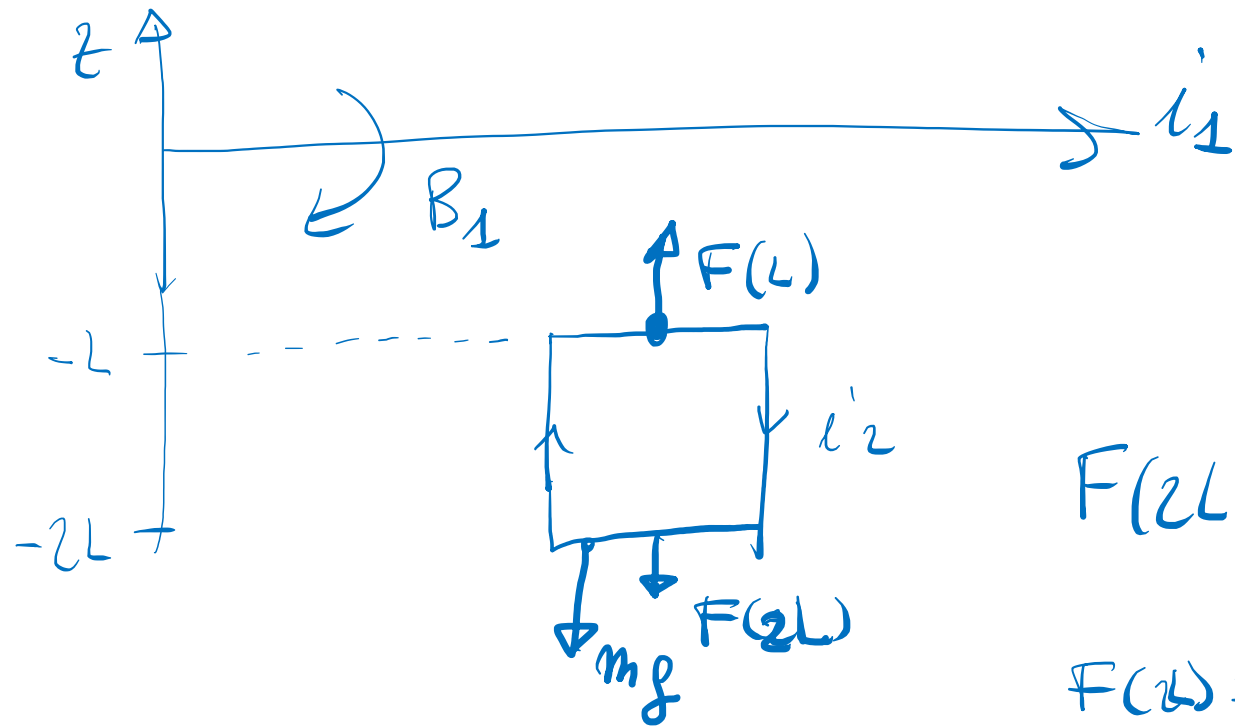
$$x = i_1 = \frac{\Delta_x}{\Delta}$$

$$y = i_2 = \frac{\Delta_y}{\Delta}$$

$$V_A - V_B = R P_2 (i\mu_1 + i\mu_2)$$

$$P_1 = \varepsilon_1 i\mu_2 \quad P_2 = \varepsilon_2 i\mu_1$$

3)



$$B(z) = \frac{\mu_0 i_1}{2\pi |z|}$$

P.6

$$F(2L) + mg = F(L)$$

$$F(2L) = B_1(2L) i_2 L \quad F(L) = B_1(L) i_2 L$$

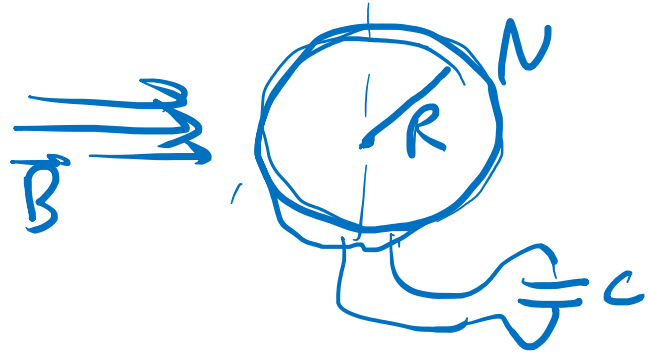
$$\frac{\mu_0 i_1 i_2 L}{2\pi 2L} + mg = \frac{\mu_0 i_1 i_2 L}{2\pi L} \rightarrow m = \frac{1}{g} \frac{\mu_0 i_1 i_2}{2\pi} \left(1 - \frac{1}{2}\right) = \frac{\mu_0 i_1 i_2}{4\pi g}$$

$$\phi(B_1) = L \int_{-L}^{2L} B_1(z') dz' = L \frac{\mu_0 i_1}{2\pi} \int_{-L}^{2L} \frac{dz'}{z'} = \frac{\mu_0 i_1}{2\pi} L \ln \frac{2L}{L} = \frac{\mu_0 i_1 L}{2\pi} \ln 2 \quad \text{entrate}$$

e
saído

em $t' = -t$

4)



$$\Phi(B) = B \pi R^2 N \cos \theta(t) \quad \boxed{P.5}$$

$$\theta(t) = \omega t \quad \Phi(B) = \pi B R^2 N \cos \omega t$$

$$f_{em}(t) = \frac{-d\Phi}{dt} = \omega \pi R^2 B N \sin(\omega t)$$

$$V_c(t) = f_{em}(t) = \frac{q_c(t)}{C} \rightarrow q_c(t) = C \cdot f_{em}(t)$$

$$q_c(t) = \omega \pi R^2 B N C \sin(\omega t)$$

$$i_c(t) = \frac{dq_c(t)}{dt} = \omega^2 \pi R^2 B N C \cos(\omega t)$$

$$P(t) = f_{em}(t) \cdot i_c(t) = \omega^3 \pi^2 R^4 B^2 N^2 C \underbrace{\sin(\omega t) \cos(\omega t)}_{\frac{1}{2} \sin(2\omega t)}$$

$$P(t) = \frac{1}{2} \omega^3 \pi^2 R^4 B^2 N^2 C \sin(2\omega t)$$

$$P_m = \frac{1}{T_0} \int^T P(t) dt = 0 \quad \boxed{T = \frac{2\pi}{\omega}}$$