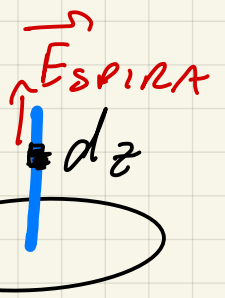


$$1) dF_z(z) = dq_2 \vec{E}_z^{SPINA}$$

$$dq_2 = \lambda_2 dz$$



$$F_z = \int_0^h \lambda_2 dz \vec{E}_z^{SPINA}$$

$$\vec{E}_z^{SPINA} = \frac{\lambda_1 R z}{2\epsilon_0 (z^2 + R^2)^{3/2}}$$

$$F_z = \frac{\lambda_1 \lambda_2 R}{2\epsilon_0} \int_0^h \frac{z dz}{(z^2 + R^2)^{3/2}} = \frac{\lambda_1 \lambda_2 R}{4\epsilon_0} \int_{R^2}^{R^2 + h^2} \frac{dy}{y^{3/2}} =$$

$$= \frac{\lambda_1 \lambda_2}{2\epsilon_0} \left(1 - \frac{R}{\sqrt{R^2 + h^2}} \right)$$

$$2) \vec{E}(n) = \frac{\Delta V(n)}{h} = \frac{Q}{h(n)}$$

$$V(n) = \frac{a n \epsilon_0}{h} + \frac{a(a-n) \epsilon_2 \epsilon_c}{h}$$

$$\vec{E}(n) = \frac{Q}{a \epsilon_0 [a \epsilon_2 + n(1 - \epsilon_2)]}$$

$$E_0(n_{MAX}) = E_{02}$$

$$n_{MAX} = \frac{a \epsilon_2 - \frac{Q}{a \epsilon_0 E_{02}}}{\epsilon_2 - 1}$$

$$= 1.2 \text{ cm}$$

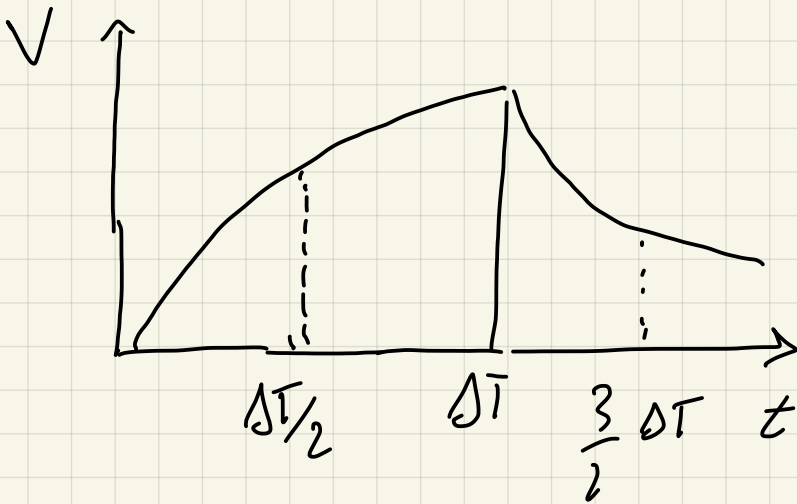
$$3) 0 < t < \Delta t \quad \tau = RC \quad \Delta V_c = \int (1 - e^{-\frac{t}{\tau}})$$

$$\Delta V_c (t = \frac{\Delta t}{2}) = 5.7 \text{ V}$$

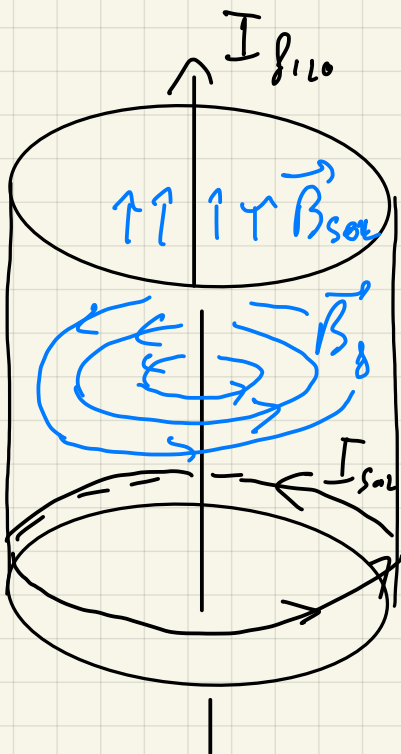
$$t > \Delta t \quad Q_c (t = \Delta t) = (f (1 - e^{-\frac{\Delta t}{\tau}})) = Q_0'$$

$$Q (t > \Delta t) = Q_0' e^{-\frac{t - \Delta t}{\tau}}$$

$$\Delta V_c (t = \frac{3}{2} \Delta t) = f (1 - e^{-\frac{\Delta t}{\tau}}) e^{-\left\{ \frac{3/2 \Delta t - \Delta t}{\tau} \right\}} = 6.9 \text{ V}$$



4)



$$B_{sol} = \mu_0 n I_{sol}$$

$$B_{fil} = \frac{\mu_0 I_{fil}}{2\pi R}$$

$$\tan \vartheta = \frac{B_{fil}}{B_{sol}} = \frac{\mu_0 I_{fil}}{2\pi R \mu_0 n I_{sol}}$$

$$\vartheta = \arctan \left\{ \frac{I_{fil}}{I_{sol}} \frac{1}{n 2\pi R} \right\} = 0.9$$

ES 5

$$\vec{E} = E_0 \cos(\vec{k} \cdot \vec{r} - \omega t)$$

$$\vec{J}_s = \epsilon_0 \frac{d\vec{E}}{dt} = -\epsilon_0 \omega E_0 \sin(\vec{k} \cdot \vec{r} - \omega t)$$

$$\langle I \rangle = \frac{E_0^2}{2Z_0}$$

$$J_s^{\text{MAX}} = \epsilon_0 (2\pi\nu) E_0 = \epsilon_0 (2\pi\nu) \sqrt{2Z_0 \langle I \rangle}$$

$$\Rightarrow J_s^{\text{MAX}} = 4.8 \times 10^{-5} \frac{\text{A}}{\text{m}^2}$$