

Associate matrici a funzioni lineari

Gia' l'abbiamo visto nel caso

$$f: \mathbb{K}^n \rightarrow \mathbb{K}^m$$



$$A \in \text{Mat}_{m \times n}(\mathbb{K}) \quad A^i := f(e_i)$$

Es: Sia $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ l'unica mappa lineare

t. c. $\begin{cases} f(e_1 + e_2) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ f(e_1 + e_2 + e_3) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ f(e_2 + e_3) = \begin{pmatrix} 1 \\ 3 \end{pmatrix} \end{cases}$

se $(e_1 + e_2, e_1 + e_2 + e_3, e_2 + e_3)$ sono base di \mathbb{R}^3
(esercizio x casa)

$$(b_1, b_2, b_3) \quad b_1 = e_1 + e_2$$

:

$$v \in \mathbb{R}^3 \Rightarrow v = \lambda_1 b_1 + \lambda_2 b_2 + \lambda_3 b_3 \quad (\exists! \lambda_1, \lambda_2, \lambda_3 \in \mathbb{R})$$

$$f(v) = f(\lambda_1 b_1 + \lambda_2 b_2 + \lambda_3 b_3) = \underbrace{\lambda_1 f(b_1) + \lambda_2 f(b_2) + \lambda_3 f(b_3)}$$

so quanto fa

Nella base (b_1, b_2, b_3) di \mathbb{R}^3

posso associare a f la matrice $A = \begin{pmatrix} f(b_1) & f(b_2) & f(b_3) \end{pmatrix}$

$$= \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix}$$

Qui ho scambiato base nel dominio di f

Potere anche cambiare base nel codominio

Potrei scrivere $c_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $c_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

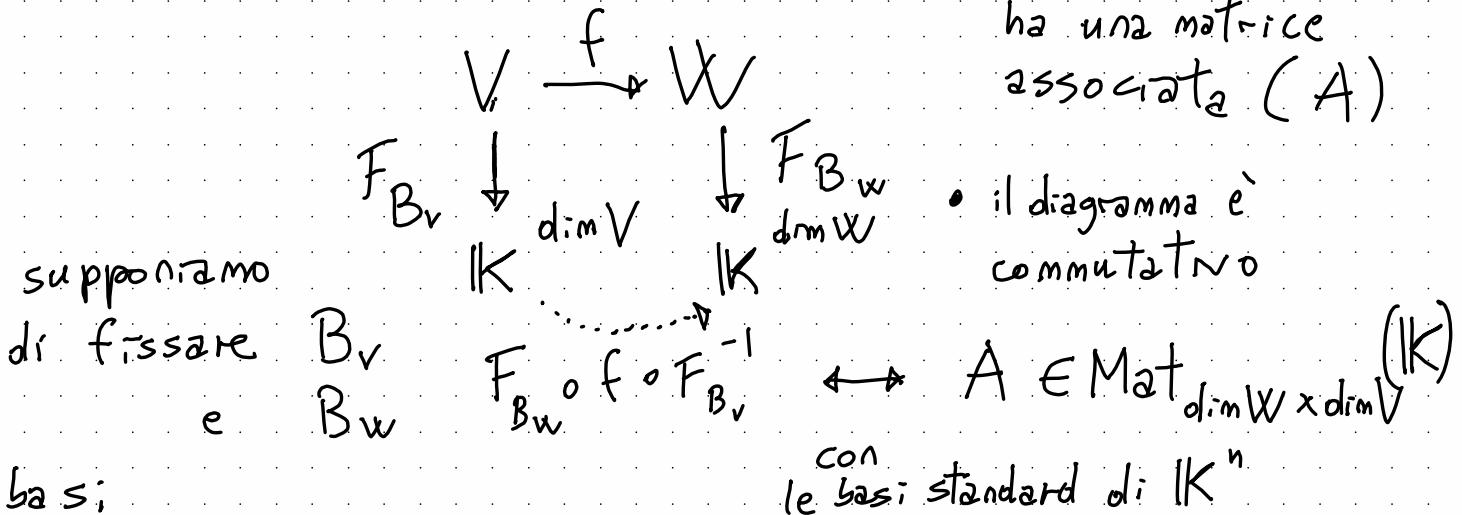
(c_1, c_2) sono base di \mathbb{R}^2

Ora la matrice associata a f : $B = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \end{pmatrix}$

$$c_1 = \underset{\equiv}{1} \cdot c_1 + \underset{\equiv}{0} c_2 \quad c_2 = \underset{\equiv}{0} c_1 + \underset{\equiv}{1} c_2 \quad \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \underset{\equiv}{-c_1} + \underset{\equiv}{2} c_2$$

In generale:

- $F_{B_W} \circ f \circ F_{B_V}^{-1}$ ha una matrice associata (A)



$$\dim U = |B|$$

$$F_B : U \rightarrow \mathbb{K}$$

Esempi (da giovedì)

valutazione di polinomi:

$$V = \mathbb{K}[x]_{\leq 2}$$

$$\varphi_1 : V \longrightarrow \mathbb{K}$$

$$p(x) \mapsto p(1)$$

vogliamo associare una matrice

quindi scegliamo delle basi

$$B_V = (1, x, x^2)$$

$$B_{\mathbb{K}} = (1) = (e_1)$$

$$V \xrightarrow{\quad \varphi_1 \quad} \mathbb{K}$$

$$\begin{array}{ccc} F_{B_V} & \downarrow & F_{B_{\mathbb{K}}} \\ \mathbb{K}^3 & \dashrightarrow & \mathbb{K} \end{array}$$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in \mathbb{K}^3$$

$$\downarrow F_{B_V}^{-1}$$

$$a \cdot 1 + b \cdot x + c \cdot x^2 \in \mathbb{K}[x]_{\leq 2}$$

$$\begin{array}{c} \downarrow \\ a+b+c \end{array}$$

$$(a+b+c) \cdot 1 \in K$$

$$\begin{array}{ccc} & F_{B_K} & \\ \downarrow & & \\ (a+b+c) & f & \\ \overbrace{F_{B_K} \circ g}^f \circ F_{B_V}^{-1} \left(\begin{pmatrix} a \\ b \\ c \end{pmatrix} \right) & = & (a+b+c) \end{array}$$

$$A = \left(f(e_1) \mid f(e_2) \mid f(e_3) \right)$$

$$= \left(\begin{matrix} 1 & 1 & 1 \end{matrix} \right)$$

$$p(x) \mapsto p(z)$$

$$\begin{array}{ccc} & \searrow & \rightarrow \\ F_{B_v} & \downarrow & \bar{\mathbb{K}} \\ \bar{\mathbb{K}}^3 & \dashrightarrow & \bar{\mathbb{K}} \\ & \downarrow & F_{B_w} \end{array}$$

$$\begin{array}{ccccccc} & -1 & & & & & \\ F_{B_v} & & & & & & \\ \left(\begin{matrix} a \\ b \\ c \end{matrix} \right) & \mapsto & a + bx + cx^2 & \mapsto & a + 2b + 4c & \mapsto & a + 2b + 4c \\ \nearrow & & \cap & & \cap & & \cap \\ \bar{\mathbb{K}}^3 & & V = \bar{\mathbb{K}}[x]_{\leq 2} & & \bar{\mathbb{K}} & & \bar{\mathbb{K}} \end{array}$$

$$A = \begin{pmatrix} 1 & 2 & 4 \end{pmatrix}$$

Ese con polinomi

$$p(x) \mapsto p(x+1)$$

$$f: V \rightarrow V$$

$$\begin{array}{ccc} V & \xrightarrow{f} & V \\ F_{B_V} \downarrow & & \downarrow F_{B_V} \\ \mathbb{K}^3 & \dashrightarrow & \mathbb{K}^3 \\ S_A & & \end{array}$$

- Scegliamo basi:

$$B_V = (1, x, x^2)$$

per dominio e codominio

- Scriviamo la composizione

$$S_A : \begin{pmatrix} a \\ b \\ c \end{pmatrix} \xrightarrow{F_{B_V}^{-1}} a + bx + cx^2 \xrightarrow{f} a + b + c + (b+2c)x + cx^2 \xrightarrow{\downarrow} \begin{pmatrix} a+b+c \\ b+2c \\ c \end{pmatrix}$$

$$S_A \left(\begin{pmatrix} a \\ b \\ c \end{pmatrix} \right) = \begin{pmatrix} a+b+c \\ b+2c \\ c \end{pmatrix}$$

$$A = \left(\begin{array}{c|c|c} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{array} \right)$$

$$A^1 = S_A(e_1)$$

$$A^2 = S_A(e_2)$$

$$A^3 = S_A(e_3)$$

Es trasposta

$$V = \text{Mat}_{2 \times 2}(\mathbb{K})$$

$$\begin{array}{ccc} V & \xrightarrow{\cdot^t} & V \\ F_{B_V} \downarrow & & \downarrow F_{B_V} \end{array}$$

$$\cdot^t : V \rightarrow V$$

$$A \mapsto A^t$$

$$\begin{array}{ccc} \mathbb{K}^4 & \xrightarrow{\quad \quad \quad} & \mathbb{K}^4 \\ S_A & \quad \quad \quad & \end{array}$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad A^t = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

- Scegliamo delle basi;

$$B_V = (E_{11}, E_{12}, E_{21}, E_{22})$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \cdots$$

- Scrivo la composizione

$$S_A : \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \mapsto 2E_{11} + bE_{12} + cE_{21} + dE_{22} = \begin{pmatrix} a \\ c \\ b \\ d \end{pmatrix}$$

$$\xrightarrow{\cdot t} \begin{pmatrix} a & c \\ b & d \end{pmatrix} \xrightarrow{F_{B_V}^{-1}} \begin{pmatrix} a \\ c \\ b \\ d \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Comandi MATLAB :

$$A = \text{sym}([\dots ; \dots])$$

Il comando $\text{null}(A)$ restituisce una matrice le cui colonne sono le soluzioni-base del sistema che definisce $\text{Ker } A$.

Es: $A = \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix}$ $\text{Ker}(A) = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid x_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}$

$$= \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid x_1 + 2x_2 = 0 \right\}$$

$$= \left\langle \begin{pmatrix} -2 \\ 1 \end{pmatrix} \right\rangle$$

$$\underline{\text{Es:}} \quad A = \begin{pmatrix} 1 & 2 & 1 & -1 \\ -1 & 1 & 2 & -2 \\ 1 & 3 & 2 & -2 \end{pmatrix} \in \text{Mat}_{3 \times 4}(\mathbb{R})$$

$$\text{Ker } A = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \in \mathbb{R}^4 \mid x_1 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} + x_3 \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} + x_4 \begin{pmatrix} -1 \\ -2 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \in \mathbb{R}^4 \mid \begin{array}{l} x_1 + 2x_2 + x_3 - x_4 = 0, \\ -x_1 + x_2 + 2x_3 - 2x_4 = 0, \\ x_1 + 3x_2 + 2x_3 - 2x_4 = 0 \end{array} \right\}$$

$$= \left\{ x \mid \begin{array}{l} x_1 + 2x_2 + x_3 - x_4 = 0 \\ 3x_2 + 3x_3 - 3x_4 = 0 \\ x_2 + x_3 - x_4 = 0 \end{array} \right\}$$

$$= \left\{ x \mid \begin{array}{l} x_1 + 2x_2 + x_3 - x_4 = 0 \\ x_2 = -x_3 + x_4 \\ 3(-x_3 + x_4) + 3x_3 - 3x_4 = 0 \end{array} \right\}$$

$$= \left\{ X \mid \begin{array}{l} x_1 + 2x_2 + x_3 - x_4 = 0 \\ x_2 = -x_3 + x_4 \\ 3(-x_3 + x_4) + 3x_3 - 3x_4 = 0 \end{array} \right\}$$

$$= \left\{ X \mid \begin{array}{l} x_1 + 2(-x_3 + x_4) + x_3 - x_4 = 0 \\ x_2 = -x_3 + x_4 \end{array} \right\}$$

$$= \left\{ X \mid \begin{array}{l} x_1 = x_3 - x_4 \\ x_2 = -x_3 + x_4 \end{array} \right\} = \left\langle \begin{pmatrix} 1 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix} \right\rangle$$

Comando MATLAB per il rango.

Def: Data una matrice $A \in \text{Mat}_{m \times n}(\mathbb{K})$
il rango di A è per definizione
la dimensione di $\text{Im } S_A$:

$$\text{rk}(A) = \text{rg}(A) = \dim \text{Im}(S_A) = \text{Col}(A)$$

$$\text{Col}(A) := \langle A^1, A^2, \dots, A^m \rangle \quad S_A: \mathbb{K}^n \rightarrow \mathbb{K}^m$$

Teorema della dimensione per la matrice

$$\dim \text{Ker}(A) + \text{rg}(A) = m$$

In MATLAB: $\text{rg}(A) =: \text{rank}(A)$

Esercizio: Sia $\mathcal{L}: \mathbb{K}^3 \rightarrow \mathbb{K}^3$ l'unica applicazione lineare t.c.

$$\mathcal{L}(e_1 + e_2) = e_1 - e_3$$

$$\mathcal{L}(e_1 + e_2 + e_3) = 2e_1 + e_2 - 2e_3$$

$$\mathcal{L}(e_2 + e_3) = e_1 + e_2 - e_3$$

- 1) Trovare la matrice A t.c. $\mathcal{L} = S_A$
- 2) Trovare le matrici che rappresenta \mathcal{L} nella base $\beta = \{e_1 + e_2, e_1 + e_2 + e_3, e_2 + e_3\}$ in partenza e canonica $\mathcal{C} = \{e_1, e_2, e_3\}$ in arrivo.
- 3) Base di $\text{Ker } \mathcal{L}$ e di $\text{Im } \mathcal{L}$.

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1) Trovare la matrice A t.c. $\mathcal{L} = S_A$

$$A = (\mathcal{L}(e_1) \mid \mathcal{L}(e_2) \mid \mathcal{L}(e_3)) \in \text{Mat}_{3 \times 3}(\mathbb{K})$$

$$e_1 = (e_1 + e_2 + e_3) - (e_2 + e_3)$$

$$\Rightarrow \mathcal{L}(e_1) = \mathcal{L}(e_1 + e_2 + e_3) - \mathcal{L}(e_2 + e_3) = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

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1) Trovare la matrice A t.c. $\mathcal{L} = S_A$

$$A = (\mathcal{L}(e_1) \mid \mathcal{L}(e_2) \mid \mathcal{L}(e_3)) \in \text{Mat}_{3 \times 3}(\mathbb{K})$$

$$e_2 = ?$$

$$e_2 = (e_1 + e_2) - e_1 \Rightarrow \mathcal{L}(e_2) = \mathcal{L}(e_1 + e_2) - \mathcal{L}(e_1) = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

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1) Trovare la matrice A t.c. $\mathcal{L} = S_A$

$$A = (\mathcal{L}(e_1) \mid \mathcal{L}(e_2) \mid \mathcal{L}(e_3)) \in \text{Mat}_{3 \times 3}(\mathbb{K})$$

$$e_3 = ?$$

$$e_3 = (e_1 + e_2 + e_3) - (e_1 + e_2) \Rightarrow \mathcal{L}(e_3) = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

$$e_3 = (e_2 + e_3) - e_2 \Rightarrow \mathcal{L}(e_3) = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

Esercizio: Sia $\mathcal{L}: \mathbb{K}^3 \rightarrow \mathbb{K}^3$ l'unica applicazione lineare t.c.

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1) Trovare la matrice A t.c. $\mathcal{L} = S_A$

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ -1 & 0 & -1 \end{pmatrix}$$

2) La matrice che rappresenta \mathcal{L} nella base B in posenza e comunque in arrivo:

$$B = \left(F_e(\mathcal{L}(e_1 + e_2)) \mid F_e(\mathcal{L}(e_1 + e_2 + e_3)) \mid F_e(\mathcal{L}(e_2 + e_3)) \right)$$

$$= \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ -1 & -2 & -1 \end{pmatrix}$$

$$\mathcal{E} = \{e_1, e_2, e_3\}$$

$$F_e: \mathbb{K}^3 \longrightarrow \mathbb{K}^3$$

$$v \longmapsto \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} : v = x_1 e_1 + x_2 e_2 + x_3 e_3$$

$$\text{oss: } F_e = \text{Id}_{\mathbb{K}^3}$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longmapsto \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$