

Matrice identità

Dato V sp. vett. esiste sempre la funzione

identità $\text{Id}_V : V \rightarrow V$ t.c. $\text{Id}_V(u) = u \quad \forall u \in V$

Oss: è lineare

Se scelgo una base B di V

$$\begin{array}{ccc} V & = & V \\ F_B \downarrow & & \downarrow F_B \\ \mathbb{K}^n & \xrightarrow{S_{\mathbb{1}_n}} & \mathbb{K}^n \end{array}$$

$\mathbb{1}_n$ è la matrice associata a Id_V
si chiama matrice identità

$$\mathbb{1}_n = (e_1 | e_2 | \dots | e_n)$$

$$\mathbb{1}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Oss: $\mathbb{1}_n$ è diagonale

(Una matrice si dice diagonale se può avere coeff. $\neq 0$ solo sulla diagonale)

Oss: i) $\mathbb{1}_n \cdot A = A$

$$\forall A \in \text{Mat}_{n \times m}(\mathbb{K})$$

($\forall m$)

ii) $A \cdot \mathbb{1}_n = A$

$$\forall A \in \text{Mat}_{m \times n}(\mathbb{K})$$

($\forall m$)

i)

$$\begin{array}{ccccc} V & \xrightarrow{L} & W & \xrightarrow{\text{Id}_W} & W \\ \downarrow & & \downarrow & & \downarrow \\ \mathbb{K}^m & \xrightarrow{S_A} & \mathbb{K}^n & \xrightarrow{S_{\mathbb{1}_n}} & \mathbb{K}^n \\ & \searrow S_{\mathbb{1}_n \cdot A} & & & \end{array}$$

$$L = \text{Id} \circ L$$



$$S_A = S_{\mathbb{1}_n \cdot A}$$

Richiamo sui cambi di base e sulla similitudine

Def:

$$L_1: V_1 \rightarrow W_1$$

mappe lineari

$$L_2: V_2 \rightarrow W_2$$

$$L_1 \sim L_2$$

quando

"simile"

$$\begin{array}{ccc} V_1 & \xrightarrow{L_1} & W_1 \\ F_V \downarrow & & \downarrow F_W \\ V_2 & \xrightarrow{L_2} & W_2 \end{array}$$

$\exists F_V, F_W$ invertibili

$$\text{t.c. } L_2 \circ F_V = F_W \circ L_1$$

$$\text{Oss: } F_W^{-1} \circ L_2 \circ F_V = L_1$$

Obiettivo: vogliamo capire quando $L_1 \sim L_2$

Supponiamo che $L_1 \sim L_2$

Oss 1: $\dim V_1 = \dim V_2$ (perché F_V è invertibile)

$\dim W_1 = \dim W_2$ (" F_W ")

Oss 2: $\text{rk } L_1 = \text{rk } L_2$

$u \in V_1$

$$\begin{array}{ccc} V_1 & \xrightarrow{L_1} & W_1 \supseteq \text{Im}(L_1) \\ F_V \downarrow & & \downarrow F_W \quad | \quad | \\ V_2 & \xrightarrow{L_2} & W_2 \supseteq \text{Im}(L_2) \end{array}$$

$$\begin{array}{c} L_1(u) \\ \downarrow \end{array}$$

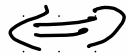
$$F_W(L_1(u))$$

$$= L_2(F_V(u))$$

questo significa che $\dim \text{Im } L_1 = \dim \text{Im } L_2$

Teorema :

$$L_1 \sim L_2$$



$$\dim V_1 = \dim V_2 \quad e$$

$$\dim W_1 = \dim W_2 \quad e$$

$$\text{rk } L_1 = \text{rk } L_2$$

Domanda: con quali basi è meglio esprimere
la matrice associata a $L: V \rightarrow W$?

$$\begin{array}{ccc} V & \xrightarrow{L} & W \\ \downarrow F_{B_V} & & \downarrow F_{B_W} \\ \mathbb{K}^n & \xrightarrow{S_A} & \mathbb{K}^m \end{array}$$

Es: (Es 2 sett 4)

$$L: V \rightarrow W$$

$$B_1 = \{v_1, v_2, v_3\}$$

$$B_2 = \{w_1, w_2, w_3, w_4\}$$

con queste basi: la mat. assoc. è

$$\begin{pmatrix} 2 & 1 & 3 \\ 3 & 0 & 6 \\ -1 & -1 & -1 \\ 1 & -1 & 3 \end{pmatrix}$$

$$\ker L = \langle -2v_1 + \underbrace{v_2 + v_3}_u \rangle$$

$$\rightarrow \mathcal{B}'_V = (-2v_1 + v_2 + v_3, v_1, v_2)$$

$$\mathcal{B}_{\text{Im}L} = (L(v_1), L(v_2))$$

$$\rightarrow \mathcal{B}'_W = (L(v_1), L(v_2), w_1, w_2)$$

$$\begin{array}{ccc} V & \xrightarrow{L} & W \\ \downarrow F_{\mathcal{B}'_V} & & \downarrow F_{\mathcal{B}'_W} \\ \mathbb{K}^3 & \longrightarrow & \mathbb{K}^4 \end{array}$$

$$\left(\begin{array}{c|c|c} F(L(u)) & F(L(v_1)) & F(L(v_2)) \\ \hline 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

In generale costruiamo basi in questo modo:

$$L: V \rightarrow W$$

$$\mathcal{B}_{\ker L} = (v_1, \dots, v_{\dim \ker L})$$

$$\mathcal{B}_V = (v_{\dim \ker L + 1}, \dots, v_{\dim V}, v_1, \dots, v_{\dim \ker L})$$

$$\mathcal{B}_{\text{Im } L} = (L(v_1), \dots, L(v_r))$$

$$\mathcal{B}_W = (L(v_1), \dots, L(v_r), w_{r+1}, \dots, w_{\dim W})$$

$r = \text{rk } L$

la matrice associata a L è $(e_1 | e_2 | e_3 | \dots | e_r | 0 | \dots | 0)$

Es di prima:

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \left(\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right) = \left(\begin{array}{c|c} \mathbb{1}_2 & \mathbb{0}_{2 \times 1} \\ \hline \mathbb{0}_{2 \times 2} & \mathbb{0}_{1 \times 1} \end{array} \right)$$

scrittura "a blocchi"

In generale

$$A = \left(\begin{array}{c|c} \mathbb{1}_r & \mathbb{0} \\ \hline \mathbb{0} & \mathbb{0} \end{array} \right)$$

$e_1 | \dots | e_r \quad 0 | \dots | 0$

Teorema:

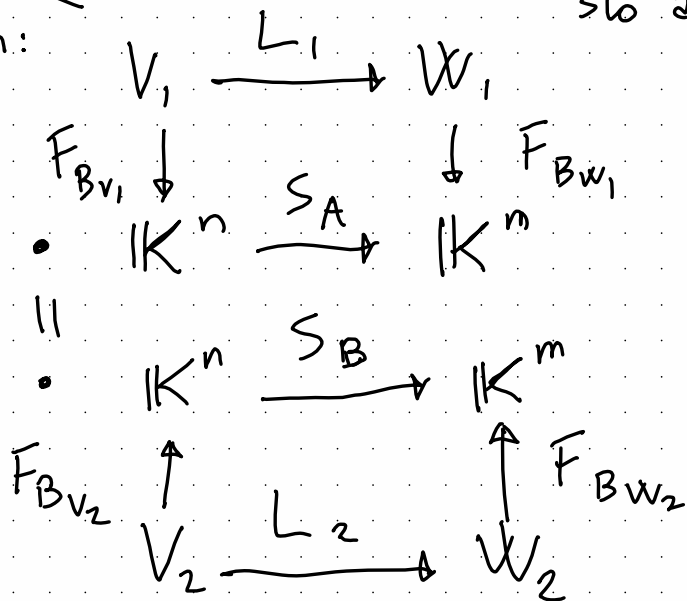
$$L_1 \sim L_2 \iff$$

$$\dim V_1 = \dim V_2 = n$$

$$\dim W_1 = \dim W_2 = m$$

$$\text{rk } L_1 = \text{rk } L_2 = r$$

Dim: \leftarrow

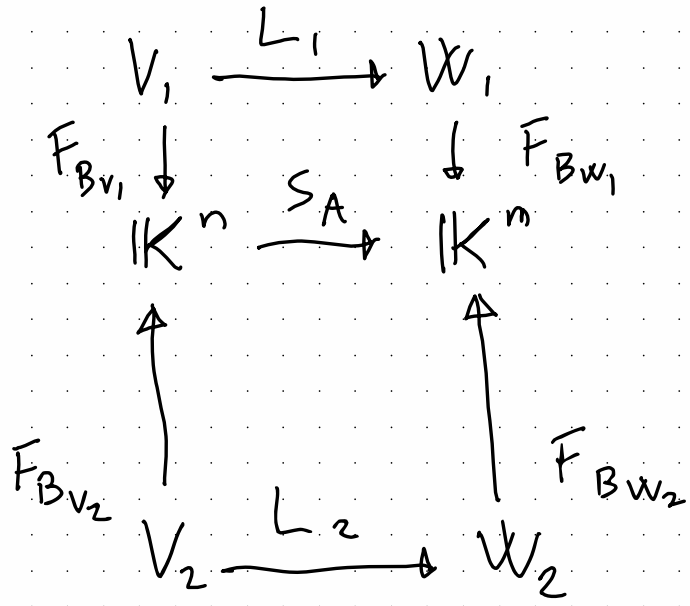


sto applicando 2 volte la procedura di prima

$$A = \left(\begin{array}{c|c} \mathbb{1}_r & 0 \\ \hline 0 & 0 \end{array} \right)$$

\parallel

$$B = \left(\begin{array}{c|c} \mathbb{1}_r & 0 \\ \hline 0 & 0 \end{array} \right)$$



quand: $F_{Bv_2}^{-1} \circ F_{Bv_1} \downarrow \quad V_1 \xrightarrow{L_1} W_1 \downarrow \quad F_{Bw_2}^{-1} \circ F_{Bw_1} \Rightarrow L_1 \sim L_2$
 $V_2 \xrightarrow{L_2} W_2$

Esercizi sulla moltiplicazione di matrici;

Es 4 Sett 4 : $L: \mathbb{K}^4 \rightarrow \mathbb{K}^4$

$$e_1 + e_2 \mapsto e_2$$

$$e_1 - e_2 \mapsto e_1$$

$$e_3 + e_4 \mapsto e_3$$

$$e_3 - e_4 \mapsto e_4$$

$$L = S_A$$

$$A = \begin{pmatrix} 1/2 & -1/2 & 0 & 0 \\ 1/2 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 1/2 \\ 0 & 0 & 1/2 & -1/2 \end{pmatrix} = \left(\begin{array}{cc|cc} 1/2 & -1/2 & & \\ 1/2 & 1/2 & & 0 \\ \hline & & 1/2 & 1/2 \\ & & 1/2 & -1/2 \end{array} \right)$$

$$B = A^{-1} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix}$$

f invertibile $\Leftrightarrow \exists g : fg = id$
 $gf = id$

L è invertibile $\Rightarrow \exists L^{-1}$
 \downarrow \downarrow
 A B



?

$$AB = \mathbb{1}_4$$

$$BA = \mathbb{1}_4$$

verif: chiamo queste identità :

$$\begin{pmatrix} \boxed{\begin{matrix} 1/2 & -1/2 \\ 1/2 & 1/2 \end{matrix}} & \begin{matrix} 0 & 0 \\ 0 & 0 \\ 1/2 & 1/2 \\ 1/2 & -1/2 \end{matrix} \\ \begin{matrix} 0 & 0 \\ 0 & 0 \end{matrix} & \begin{matrix} 0 & 0 \\ 1 & 1 \\ 0 & 0 \\ 0 & 0 \end{matrix} \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} A_1 & 0 \\ 0 & A_2 \end{pmatrix} \begin{pmatrix} B_1 & 0 \\ 0 & B_2 \end{pmatrix} = \begin{pmatrix} A_1 B_1 + 0 \cdot 0 & A_1 \cdot 0 + 0 B_2 \\ 0 \cdot B_1 + A_2 \cdot 0 & 0 \cdot 0 + A_2 B_2 \end{pmatrix} =$$

$$= \begin{pmatrix} A_1 B_1 & 0 \\ 0 & A_2 B_2 \end{pmatrix}$$

$$A_1 B_1 = \begin{pmatrix} 1/2 & -1/2 \\ 1/2 & 1/2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}_2$$

$$A_2 B_2 = \quad \quad \quad = \mathbb{1}_2$$

$$= \begin{pmatrix} \mathbb{1}_2 & 0 \\ 0 & \mathbb{1}_2 \end{pmatrix} = \mathbb{1}_4$$

L'importante è che i blocchi
abbiano taglie compatibili:

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}^2 = \left(\begin{array}{c|cc} 1 & 1 & 1 \\ \hline 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)^2 = \left(\begin{array}{c|c} \mathbb{1}_1 & A \\ \hline 0 & \mathbb{1}_2 \end{array} \right)^2$$

$$\begin{pmatrix} \mathbb{1}_1 & A \\ 0 & \mathbb{1}_2 \end{pmatrix} \begin{pmatrix} \mathbb{1}_1 & A \\ 0 & \mathbb{1}_2 \end{pmatrix} = \begin{pmatrix} \mathbb{1}_1 \mathbb{1}_1 + A \cdot 0 & \mathbb{1}_1 \cdot A + A \cdot \mathbb{1}_2 \\ 0 \mathbb{1}_1 + \mathbb{1}_2 \cdot 0 & 0 \cdot A + \mathbb{1}_2 \mathbb{1}_2 \end{pmatrix}$$

$$= \begin{pmatrix} \mathbb{1}_1 & 2A \\ 0 & \mathbb{1}_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \cancel{\begin{pmatrix} \mathbb{1}_1 & A \\ 0 & \mathbb{1}_2 \end{pmatrix}}$$

In generale non mi sogno nemmeno di pensare

$$\cancel{AB \neq BA}$$

con A, B matrici

$$AB \quad A \in \text{Mat}_{n \times m} \quad B \in \text{Mat}_{m \times p} \quad \rightarrow n \times p$$

$$BA \quad \text{solo se } n = p \quad \rightarrow m \times m$$

se $n \neq m$ AB, BA non hanno la stessa taglia

$$n = m = p$$

$$\text{Es: } A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$AB = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix}$$
$$\neq$$
$$BA = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

Se $AB = BA$ dico che A, B "commutano"

$$\text{Es } \mathbb{K}^3 \xrightarrow{L_1} \mathbb{K}^2$$

$$L_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$L_1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$L_1 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\mathbb{K}^2 \xrightarrow{L_2} \mathbb{K}^2$$

$$L_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$L_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Trovare la matrice associata M a $L_2 \circ L_1$, nelle basi standard di \mathbb{K}^3 e \mathbb{K}^2 .

$$\text{Sol: } L_1 \text{ in basi: } B_1 = \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) \quad B_2 = \text{standard}$$

$$L_1 \leftrightarrow A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \end{pmatrix}$$

$$L_2 \leftrightarrow B = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$$

B_3, B_4 analog.

$$\begin{array}{ccccccc}
 \bullet) & \mathbb{K}^3 & = & \mathbb{K}^3 & \xrightarrow{L_1} & \mathbb{K}^2 & = & \mathbb{K}^2 & \xrightarrow{L_2} & \mathbb{K}^2 & \xrightarrow{A_2} \\
 & \downarrow F & & \downarrow F_{B_1} & & \downarrow F & & \downarrow F_{B_3} & & \downarrow F & \\
 & \mathbb{K}^3 & \xleftarrow{C_{B_1, \text{std}}} & \mathbb{K}^3 & \xrightarrow{S_A} & \mathbb{K}^2 & \xleftarrow{C_{B_3, \text{std}}} & \mathbb{K}^2 & \xrightarrow{S_B} & \mathbb{K}^2 &
 \end{array}$$

$$\bullet) \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$$

•) multiply:

$$\begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} = M$$

$$\begin{pmatrix} 1/2 & -1/2 \\ 1/2 & 1/2 \end{pmatrix}$$