

o) Es3 set 11 con MATLAB (Diagonalizzazione)

o) $\mathcal{L}: V \rightarrow V$ endomorfismo lineare.

Diciamo che un sottospazio vettoriale $U \subseteq V$ è \mathcal{L} -invariante se $\mathcal{L}(U) \subseteq U$ ovvero se $\forall u \in U \quad \mathcal{L}(u) \in U$.

o) Teorema spettrale:

$$A = A^t, \quad \lambda \in Sp(A) \subset \mathbb{R}$$

$$\{v_1, \dots, v_k\} \text{ base } V_\lambda(A) = \text{Ker}(\lambda I_n - A)$$

$$\rightarrow \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\} \text{ base di } \mathbb{R}^n.$$

$$W = \langle v_{k+1}, \dots, v_n \rangle = V_\lambda(A)^\perp, \quad \mathbb{R}^n = V_\lambda(A) \oplus W.$$

W è A -invariante: $w \in W \quad Aw \in W : v \in V_\lambda(A)$

$$v \cdot Aw = Av \cdot w = \lambda v \cdot w = \lambda (v \cdot w) = 0$$

$\Rightarrow w \in V_\lambda(A)^\perp = W.$

Gram-Schmidt

$$B = \left\{ v_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\} \subset \mathbb{R}^4$$

Applichiamo l'algoritmo di G-S a B :

$$F_1 = v_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$F_2 = v_2 - \text{pr}_{F_1}(v_2) = v_2 - \frac{v_2 \cdot F_1}{F_1 \cdot F_1} v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{aligned} F_3 &= v_3 - \text{pr}_{\langle F_1, F_2 \rangle}(v_3) = v_3 - \frac{v_3 \cdot F_1}{F_1 \cdot F_1} F_1 - \frac{v_3 \cdot F_2}{F_2 \cdot F_2} F_2 \\ &= \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} - \frac{1}{1} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \end{aligned}$$

$$E_1 = \frac{1}{\|F_1\|} F_1, \quad E_2 = \frac{1}{\|F_2\|} F_2, \quad E_3 = \frac{1}{\|F_3\|} F_3$$

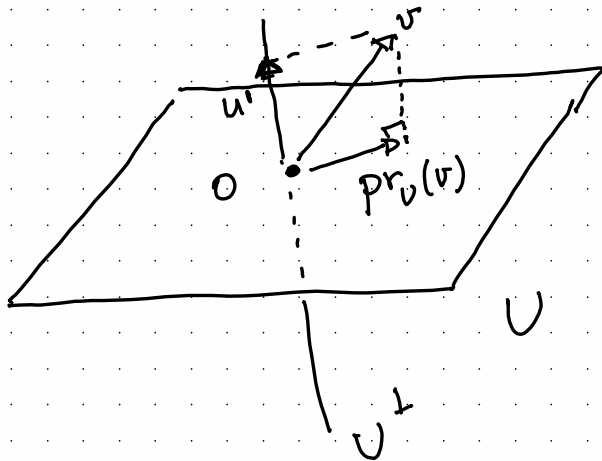
$U \subset \mathbb{R}^n$, sottosp. vettoriale.

$$\mathbb{R}^n = U \oplus U^\perp$$

$$\text{pr}_U : \mathbb{R}^n \longrightarrow \mathbb{R}^n$$

$$v = u + u' \longmapsto u$$

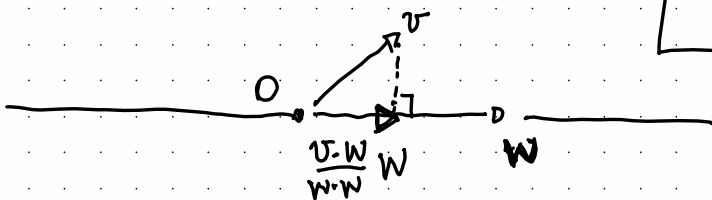
$$u \in U, u' \in U^\perp$$



$$\text{dist}(P, U) = \|P - \text{pr}_U(P)\|$$

$$U = \langle w \rangle, w \neq 0,$$

$$\text{pr}_U(v) = \frac{v \cdot w}{w \cdot w} w$$



Proiezione ortogonale su sottospazi affini.

$$P \in \mathbb{R}^n \quad U = X_0 + U_0 \subset \mathbb{R}^n \text{ s.sp. affine.}$$

$$\text{pr}_U(P) = X_0 + \text{pr}_{U_0}(P - X_0)$$

Es: Trovare le forme canonica metrica e affine della conica C_p dove

$$p(x, y) = 5x^2 + 4xy + 2y^2 - 2x + 4y - 1$$

specificando i cambiamenti di coordinate.

Sol.:

$$p(x) = x^t A x + 2 b \cdot x + f \quad x = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$A = \begin{pmatrix} 5 & 2 \\ 2 & 2 \end{pmatrix} \quad b = \begin{pmatrix} -1 \\ 2 \end{pmatrix} \quad f = -1 \quad x^2 + y^2 + \lambda_3 z^2 = 0$$

$$sg(A) = ?$$

$$\text{Tr}(A) = \lambda_1 + \lambda_2 = 7 > 0$$

$$\det(A) = \lambda_1 \lambda_2 = 6 > 0$$

$$\Rightarrow \lambda_1, \lambda_2 > 0$$

$$\Rightarrow sg(A) = (2, 0).$$

$$\begin{aligned} q_{\hat{A}}(x) &= x^t \hat{A} x = 5x^2 + 2y^2 - z^2 + 4xy - 2xz + 4yz \Big|_{z=1} \\ &= 5x^2 + 2y^2 - 1 + 4xy - 2x + 4y = p(x) \end{aligned}$$

$$p(x) = x^t A x + 2 b \cdot x + f \quad x = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$A = \begin{pmatrix} 5 & 2 \\ 2 & 2 \end{pmatrix} \quad b = \begin{pmatrix} -1 \\ 2 \end{pmatrix} \quad f = -1$$

1) Diagonaliziere orthogonalmente A :

$$P_A(x) = x^2 - 7x + 6$$

$$x_{1,2} = \frac{7 \pm \sqrt{49 - 24}}{2} = \frac{7 \pm \sqrt{25}}{2} = \frac{7 \pm 5}{2} = \begin{cases} 6 \\ +1 \end{cases}$$

$$P_A(x) = (x-6)(x-1)$$

Sie λ : $\lambda^2 - 7\lambda + 6 = 0$

$$\begin{aligned} V_\lambda(A) &= \text{Ker}(\lambda \mathbb{1}_2 - A) = \text{Ker} \begin{pmatrix} \lambda - 5 & -2 \\ -2 & \lambda - 2 \end{pmatrix} = \\ &= \text{Ker} \begin{pmatrix} 1 & \frac{\lambda - 2}{-2} \\ \lambda - 5 & -2 \end{pmatrix} = \text{Ker} \begin{pmatrix} 1 & -\frac{1}{2}(\lambda - 2) \\ 0 & -2 + \frac{1}{2}(\lambda - 2)(\lambda - 5) \end{pmatrix} \end{aligned}$$

$$\text{Ker} \begin{pmatrix} 1 & -\frac{1}{2}(\lambda-2) \\ 0 & -2 + \frac{1}{2}(\lambda-2)(\lambda-5) \end{pmatrix} = \text{Ker} \begin{pmatrix} 1 & -\frac{1}{2}(\lambda-2) \\ 0 & -2 + \frac{1}{2}4=0 \end{pmatrix}$$

$$(\lambda-2)(\lambda-5) = \lambda^2 - 7\lambda + 10 = -6 + 10 = 4$$

$$= \text{Ker} \left(1, -\frac{(\lambda-2)}{2} \right) = \left\langle \begin{pmatrix} 1 \\ \frac{2}{(\lambda-2)} \end{pmatrix} \right\rangle = \left\langle \begin{pmatrix} \lambda-2 \\ 2 \end{pmatrix} \right\rangle$$

$$V_6 = \left\langle \begin{pmatrix} 4 \\ 2 \end{pmatrix} \right\rangle = \left\langle \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right\rangle \quad V_1 = \left\langle \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right\rangle$$

$$\begin{pmatrix} 5 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 12 \\ 6 \end{pmatrix} = 6 \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 \\ 1 \end{pmatrix} \text{ \u00e9 um autovetor de autovalor 6.}$$

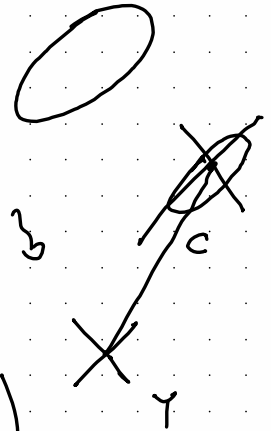
$$\begin{pmatrix} 5 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix} = 1 \begin{pmatrix} -1 \\ 2 \end{pmatrix} \Rightarrow \begin{pmatrix} -1 \\ 2 \end{pmatrix} \text{ \u00e9 autovetor de autovalor 1.}$$

$$v_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$E_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$E_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$



$$B = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} \Rightarrow B^t A B = D = \begin{pmatrix} 6 & 0 \\ 0 & 1 \end{pmatrix}$$

Facciamo il cambio di coordinate

$$\textcircled{1} \boxed{X = BY} \quad \text{ovvero} \quad \begin{cases} x_1 = \frac{2}{\sqrt{5}} y_1 - \frac{1}{\sqrt{5}} y_2 \\ x_2 = \frac{1}{\sqrt{5}} y_1 + \frac{2}{\sqrt{5}} y_2 \end{cases}$$

$$\begin{aligned} p(x) &= x^t A x + 2b \cdot x + f = (BY)^t A (BY) + 2b \cdot BY + f \\ &= Y^t B^t A B Y + 2B^t b \cdot Y + f = Y^t D Y + 2B^t b \cdot Y + f \\ &= q(Y) \end{aligned}$$

2) Trasliamo : $Y = Z + C$ dove C serve
per ridurre il Termine lineare $2 B^t b \cdot Y$

$$q(Y) = Y^t D Y + 2 B^t b \cdot Y + f$$

$$= 6 y_1^2 + y_2^2 + \frac{5}{\sqrt{5}} y_2 - 1$$

$$B^t b = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix}^t \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \frac{1}{\sqrt{5}} \begin{pmatrix} 0 \\ 5 \end{pmatrix}$$

$$q(Y) = \underset{\substack{\uparrow \\ Y=Z+C}}{(Z+C)^t} D (Z+C) + 2 B^t b \cdot (Z+C) + f$$

$$= \underline{Z^t D Z} + \underline{Z^t D C} + \underline{C^t D Z} + C^t D C +$$

$$+ 2 \underline{B^t b \cdot Z} + 2 B^t b \cdot C + f$$

$$= Z^t D Z + 2 (D C + B^t b) \cdot Z + q(C)$$

Cerchiamo C t.c. $DC + B^t b = 0_{\mathbb{R}^2}$:

$$\begin{pmatrix} 6 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} + \frac{1}{\sqrt{5}} \begin{pmatrix} 0 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} 6c_1 = 0 \\ c_2 = -\frac{5}{\sqrt{5}} = -\sqrt{5} \end{cases}$$

$$C := \begin{pmatrix} 0 \\ -\sqrt{5} \end{pmatrix}$$

Se effettuiamo il cambiamento di coordinate

② $\boxed{Y = Z + C}$ ovvero $\begin{cases} y_1 = z_1 \\ y_2 = z_2 - \sqrt{5} \end{cases}$
otteniamo

$$p(X) = q(Y) = 6z_1^2 + z_2^2 + q\left(\begin{pmatrix} 0 \\ -\sqrt{5} \end{pmatrix}\right)$$

$$q(Y) = 6y_1^2 + y_2^2 + \sqrt{5}y_2 - 1$$

$$q\left(\begin{pmatrix} 0 \\ -\sqrt{5} \end{pmatrix}\right) = 5 - 5 - 1 = -1$$

$\Rightarrow C_p$ è metricamente equivalente alla conica

$$6z_1^2 + z_2^2 - 1 = 0$$

ovvero

$$\frac{z_1^2}{\left(\frac{1}{\sqrt{6}}\right)^2} + z_2^2 = 1 \quad \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \right)$$

che è un' ellisse reale.

$$\textcircled{3} \quad z_1 = \frac{x}{\sqrt{6}} \quad z_2 = y \quad \Rightarrow$$

$$\boxed{x^2 + y^2 - 1 = 0}$$

forma canonica
affine di C_p .

Classificazione metrica :

$$\lambda_1 x^2 + \lambda_2 y^2 + \lambda_3$$

$$Sp(\hat{A})$$

$$\lambda_1 x^2 - 2k y$$

(parabola)

$$\hat{A} = \left(\begin{array}{c|c} A & b \\ \hline b^t & f \end{array} \right) \quad \hat{A}' = \left(\begin{array}{c|c} A' & b' \\ \hline b'^t & f' \end{array} \right)$$

$$\hat{A} \sim \hat{A}' \stackrel{\text{def}}{\iff} \exists \hat{B} = \left(\begin{array}{c|c} B & c \\ \hline 0 & 1 \end{array} \right) \text{ t.c.}$$

$$\hat{B}^t \hat{A} \hat{B} = \hat{A}', \quad B \text{ \u00e9 invertibile.}$$

$$\iff B^t A B = A'$$

$$\text{rg}(A|b) = \text{rg}(A'|b')$$

Es:

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix}$$

$$\det A = \det \begin{pmatrix} 1 & 1 & 2 \\ 0 & -2 & -1 \\ 0 & -1 & -5 \end{pmatrix} = 9 \neq 0$$

$$P_A(x) = \det(x \mathbb{1}_3 - A) = \det \begin{pmatrix} x-1 & -1 & -2 \\ -1 & x+1 & -1 \\ -2 & -1 & x+1 \end{pmatrix}$$

$$= \det \begin{pmatrix} 1 & -x-1 & 1 \\ x-1 & -1 & -2 \\ -2 & -1 & x+1 \end{pmatrix}$$

$$= \det \begin{pmatrix} 1 & -x-1 & 1 \\ 0 & -1+(x-1)(x+1) & -2-(x-1) \\ 0 & -3-2x & x+3 \end{pmatrix}$$

$$= \det \begin{pmatrix} x^2-2 & -x-1 \\ -3-2x & x+3 \end{pmatrix}$$

$$= \det \begin{pmatrix} x^2 - 2 & -x - 1 \\ -3 - 2x & x + 3 \end{pmatrix}$$

$$= (x^2 - 2)(x + 3) + (x + 1)(-3 - 2x)$$

$$= \underline{x^3} + \underline{3x^2} - \underline{2x} - \underline{6} - \underline{3x} - \underline{2x^2} - \underline{3} - \underline{2x}$$

$$= x^3 + x^2 - 7x - 9$$

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix}$$

$$\text{Tr}(A) = -1$$

$$\text{Tr}(A^2) = 6 + 3 + 6 = 15$$

$$\frac{1}{2} (1 - 15) = -7 \quad \checkmark$$

Teorema di Cayley-Hamilton:

$$A^3 + A^2 - 7A - 9\mathbb{1}_3 = 0_3$$

$$\Rightarrow A(A^2 + A - 7\mathbb{1}_3) = 9\mathbb{1}_3 \Rightarrow$$

$$A^{-1} = \frac{1}{9} (A^2 + A - 7\mathbb{1}_3)$$

$$A^{-1} = \frac{1}{9} (A^2 + A - 7I_3)$$

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 6 & 2 & 1 \\ 2 & 3 & 0 \\ 1 & 0 & 6 \end{pmatrix}$$

$$A^2 + A - 7I_3 = \begin{pmatrix} 6 & 2 & 1 \\ 2 & 3 & 0 \\ 1 & 0 & 6 \end{pmatrix} + \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix} - \begin{pmatrix} 7 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 7 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 3 & 3 \\ 3 & -5 & 1 \\ 3 & 1 & -2 \end{pmatrix} \begin{pmatrix} 1 & 1 & 2 \\ 1 & -1 & 1 \\ 2 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 9 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{pmatrix} \checkmark$$

$$A^{-1} = \frac{1}{9} \begin{pmatrix} 0 & 3 & 3 \\ 3 & -5 & 1 \\ 3 & 1 & -2 \end{pmatrix}$$

